

# Shock Capturing using Neural Networks

Aaron Larsen  
Mentor: Britton Olson

August 27, 2020

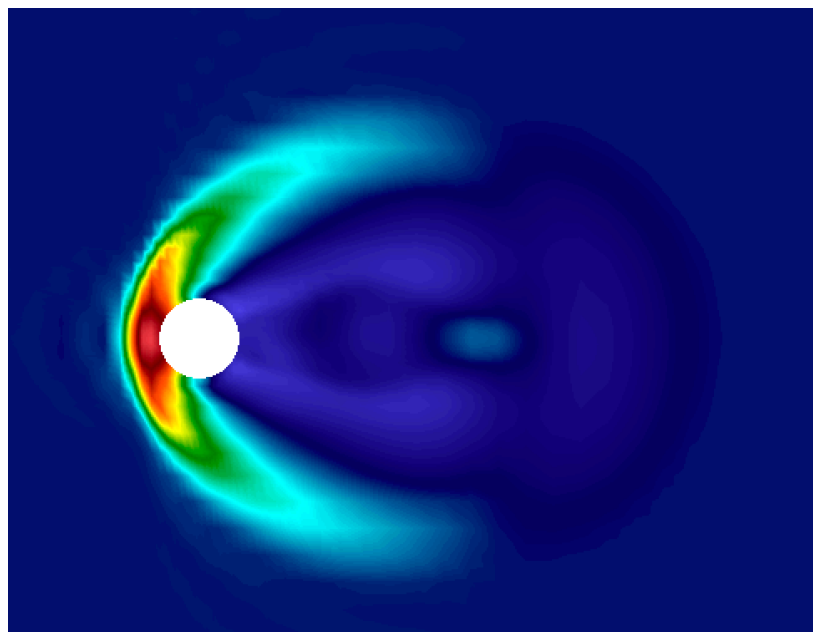


# Introduction: Shock waves occur in many mediums and have a large impact on experimental design

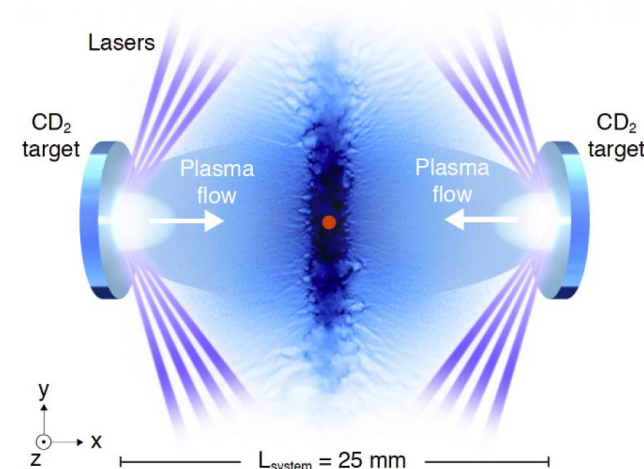
- **Shock waves** are a sharp change in pressure that moves through a medium
- **Shock waves** carry energy, which dissipates at the front of the shock wave
- **Shock waves** have a great impact on a wide variety of engineering and scientific applications



Jet flying at supersonic speeds

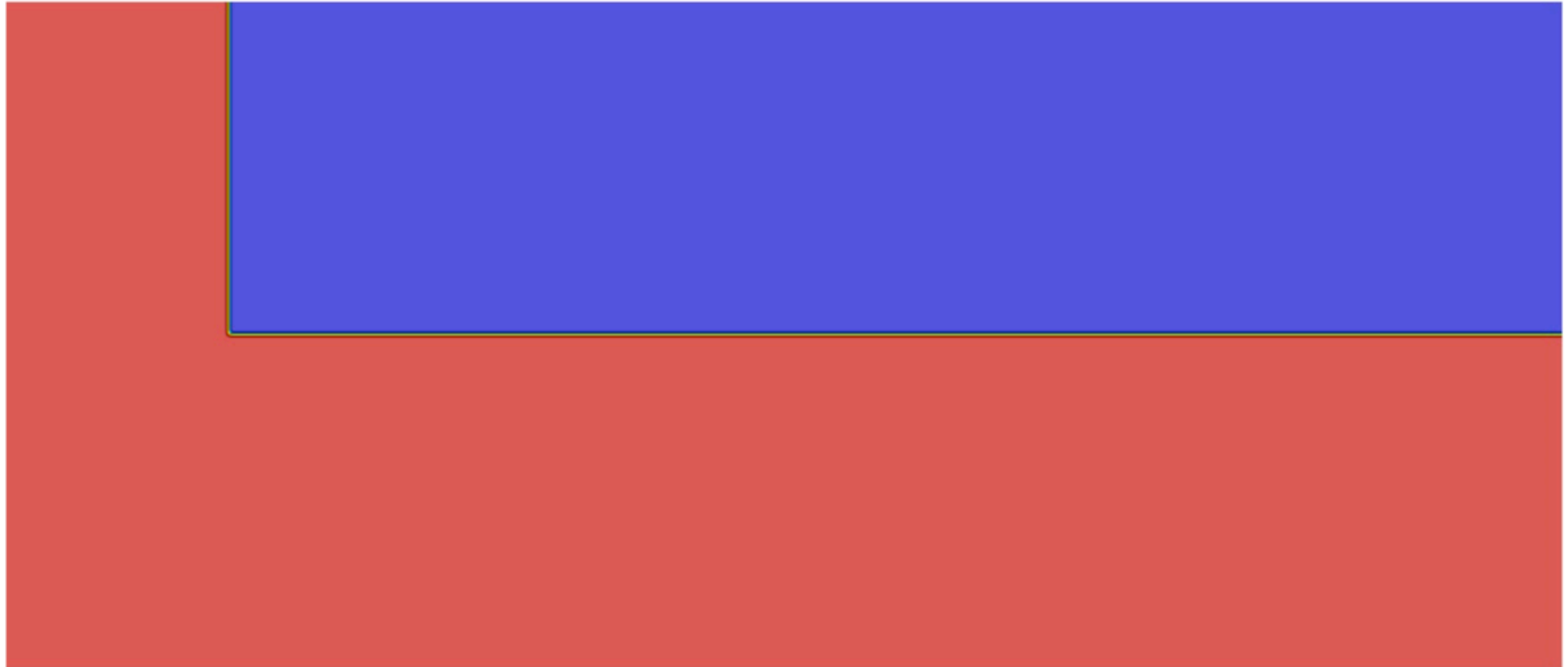


Supersonic flow past a cylinder at Mach 2



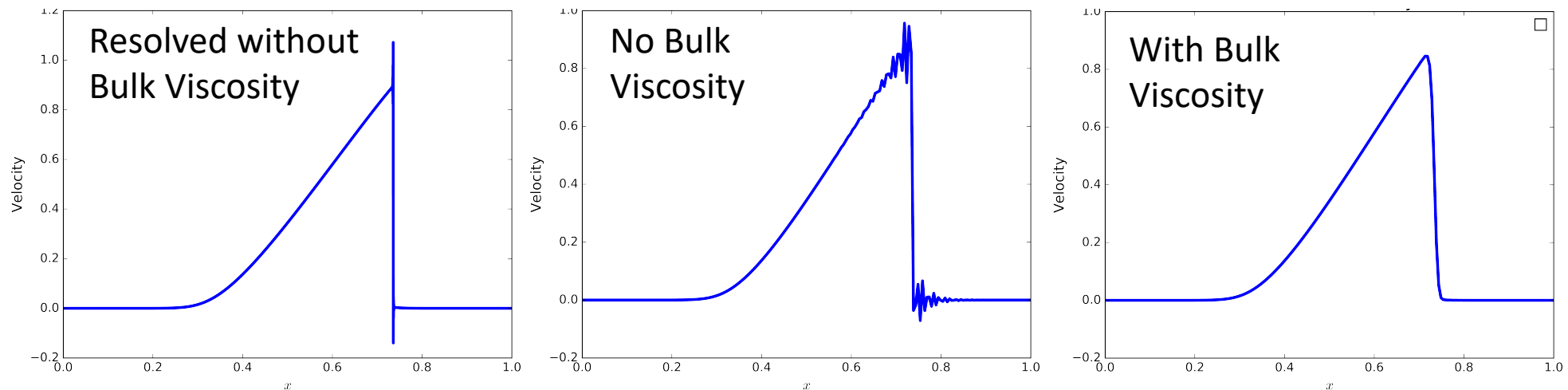
Simulating shock waves in supernova remnants

# Introduction: Shock waves occur in many mediums



# Introduction: Shock capturing is necessary to resolve shock-dominated problems

- In non-linear hyperbolic PDEs like the Euler equations, shock waves become unresolvable singularities
- Differentiating across a shock leads to Gibbs Oscillations
- Error manifests as oscillations occur because of unresolved features
- **Shock capturing** is used in hydrodynamic simulations to numerically resolve shock waves



# Miranda uses a high-order artificial viscosity operator for shock capturing

- **Artificial viscosity (AV)** is a type of shock capturing used in simulations and can be computationally expensive to compute
- AV creates features that are resolved, thus making unresolved shock waves resolved
- Miranda solves the hydrodynamics equations to high-order accuracy in space (10th) and time (4th)
- Calculating AV and other artificial diffusivities in Miranda can account for >50% of the runtime

- AV operator: 
$$\beta^* = C_\beta \rho \overline{\left\| \frac{\partial^r}{\partial x^r} (\nabla \cdot \mathbf{u}) \right\|} \Delta x^{r+2}$$

# Tools

- TensorFlow and Keras

- Open source machine learning platform
- Developed by Google
- Python package



- Pyranda

- Mini-App of Miranda
- Solves PDEs using 4<sup>th</sup> order Runge-Kutta in time, 10<sup>th</sup> order finite difference in space
- Specify equations of motion and initial conditions and grid spacing

- Python

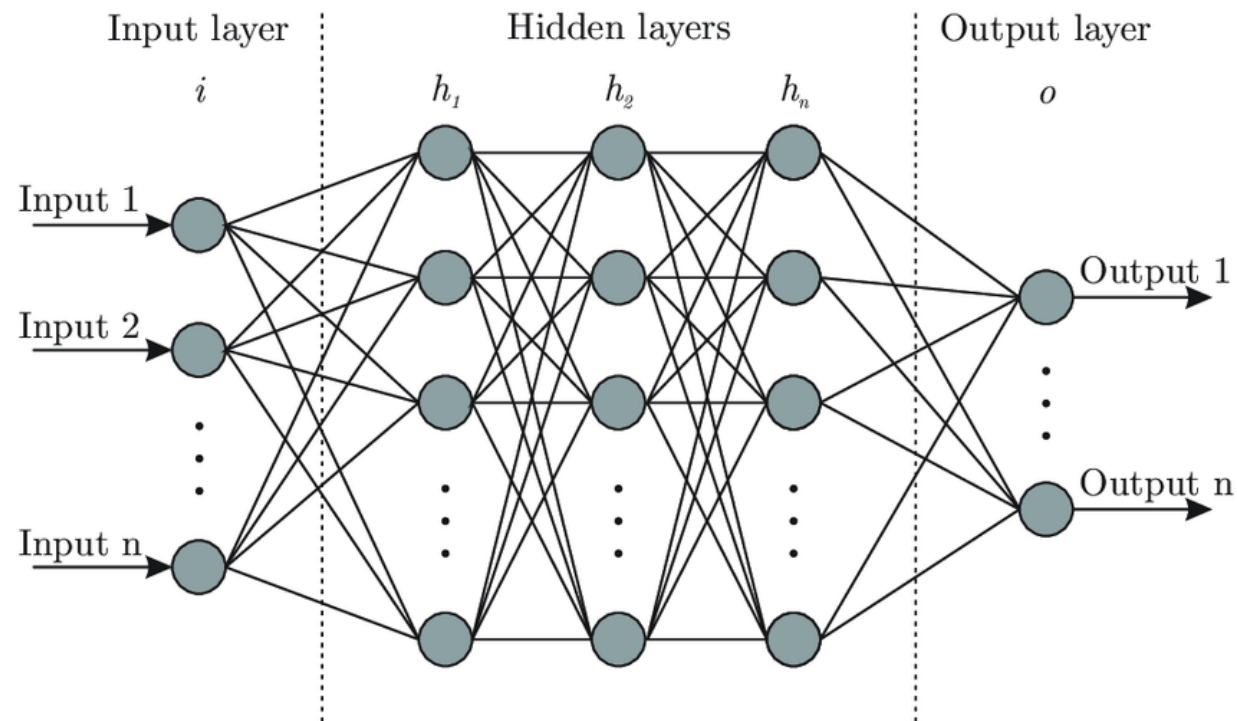
- Scipy – Analysis via error norms
- Matplotlib – Visualization



# TensorFlow

# Neural networks can be used as a regression model

- Artificial neural networks (NN) are computer models that mimic the structure of the human brain composed of layers.
- Perceptrons (nodes) compose each layer of the NN
- Each perceptron learns weights in order to maximize the objective function
- These weights are determined through the analysis of training datasets.
- Regression: A NN uses weights learned through training to predict the outputs based on inputs



# Primary objectives for summer research project

---

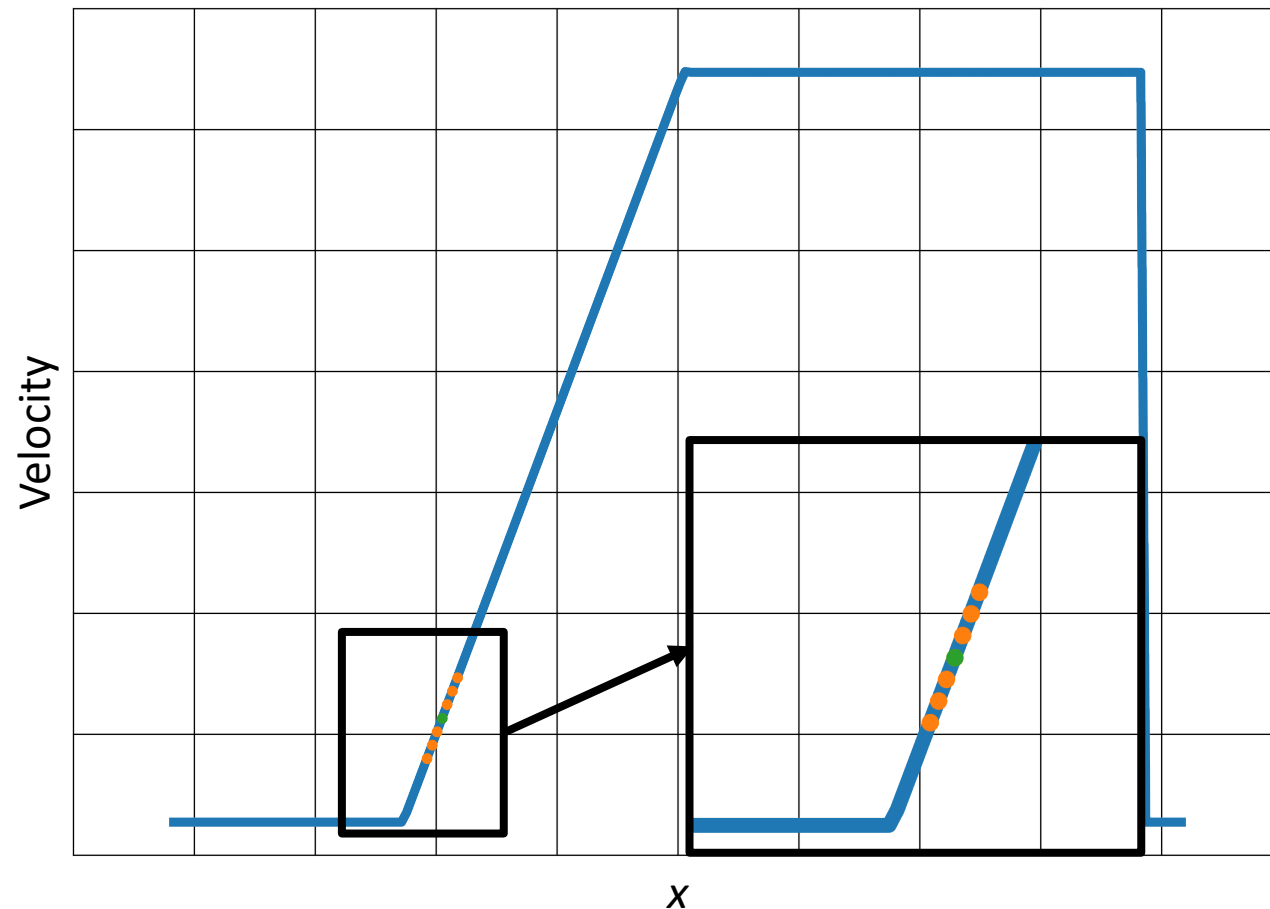
1. Can a NN accurately predict AV?
  - Gather representative training data
  - Train a neural network model
  - Apply the model to shock dominated problems and assess its accuracy
2. Can a NN be optimized to decrease the computational cost of computing AV?



# Creating a training dataset with shock-dominated test problems

1. A shock-dominated test problem using the traditional AV operator
2. Use a stencil to make an array of velocity values near the point of interest
  - a. Velocity values before and after the point are collected
3. The corresponding AV value for the point of interest is collected

4.  $data[0, j] = \beta[i]$   
 $data[1 : 7, j] = u[i - 3 : i + 3]$



# Using nondimensionalization to create a universal model

- Due to different scales of shock-dominated problems, a model trained with a specific Mach number, nondimensionalizing needs to be used
- Velocity
  - $u^* = u/c_s$
- Artificial Viscosity
  - $\beta^* = \beta/\rho/c_s/\Delta x$
- NOTE: In situations where the shock occurs in multiple directions, symmetrical data gathering is needed
  - Using a 1D simulation
    - Collect from left to right
    - Duplicate and flip

# Training a neural network to approximate the AV operator

- Software: TensorFlow — Keras
- Neural Network Structure
  - 3 Sequential layers
  - Each layer is dense (all nodes are interconnected)
  - ReLU activation function
  - Loss Function: MSE
- The neural network is reduced to a regression model
- 80% of the dataset collected from the shock-dominated problem was used as training data
- 20% of the dataset was used as validation data
- 100 epochs were used to generate the model

# Implementation and Analysis of the neural-network-based AV operator

■ AV operator:  $\beta^* = C_{\beta\rho} \overline{\frac{\partial^r}{\partial x^r} (\nabla \cdot \mathbf{u})} \Delta x^{r+2}$   $\Longrightarrow$  NN-AV operator:  $\beta^* = NN_{AV}(\mathbf{u})$

■ During each step in 4<sup>th</sup> order Runge-Kutta:

- Use a stencil to collect an array of velocity values for each point in the domain
  - $u[i-3:i+3]$
- Use the NN to predict the AV values

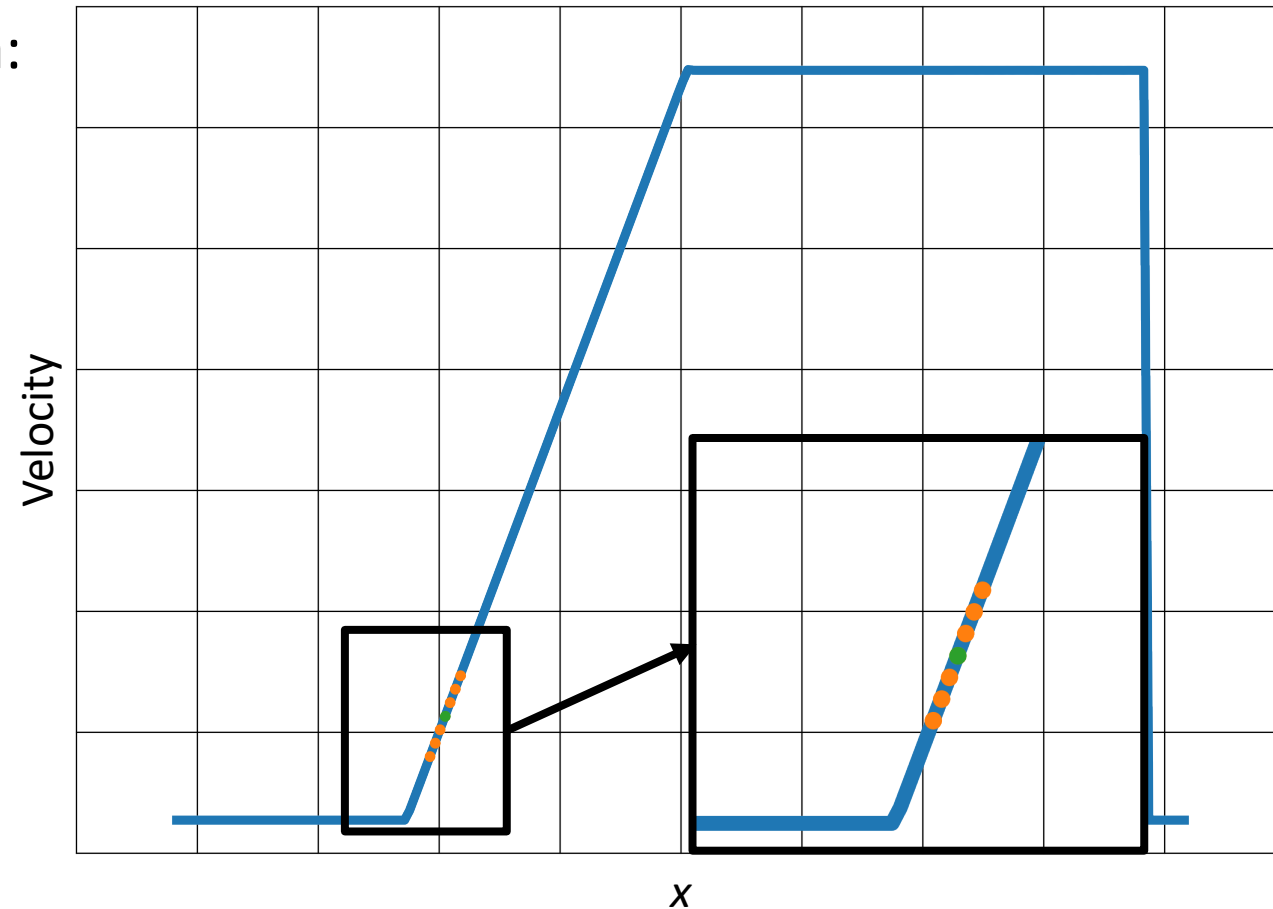
$$\beta_{ML_i} = NN_{AV}(u[i-3:i+3])$$

- Substitute the predicted AV values from NN model into the simulation

■ Analysis

- Compare NN-AV results and traditional AV data with highly resolved simulations using

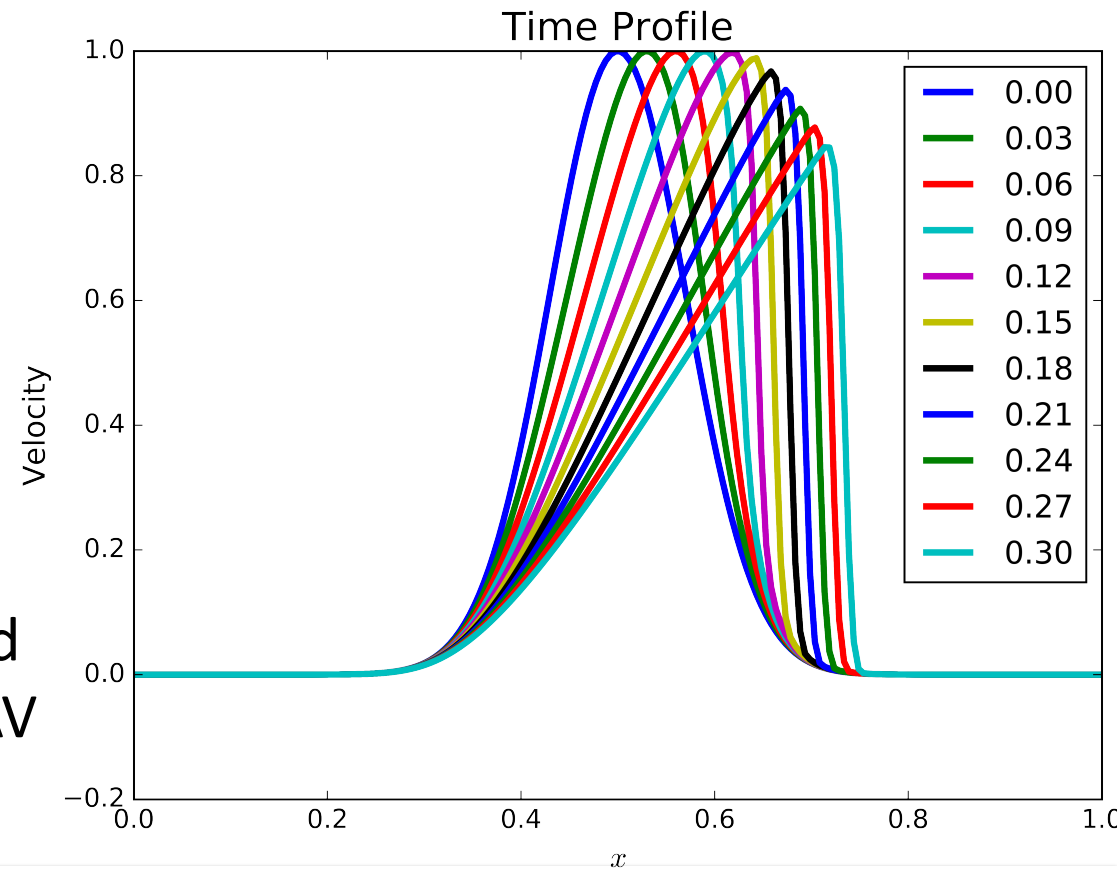
$L_1, L_2, L_\infty$  errors in density



# The Viscous Burgers' Equation

$$\frac{\partial u}{\partial t} = -u \frac{\partial u}{\partial x} + \nu \frac{\partial^2 u}{\partial x^2}$$

- Single variable hyperbolic PDE that allows for shock waves
- $\nu$  is the artificial viscosity term, no physical viscosity is used
- A neural network model was trained on a simple breaking wave
- This model was applied to the same problem and compared with the results from the traditional AV calculation.

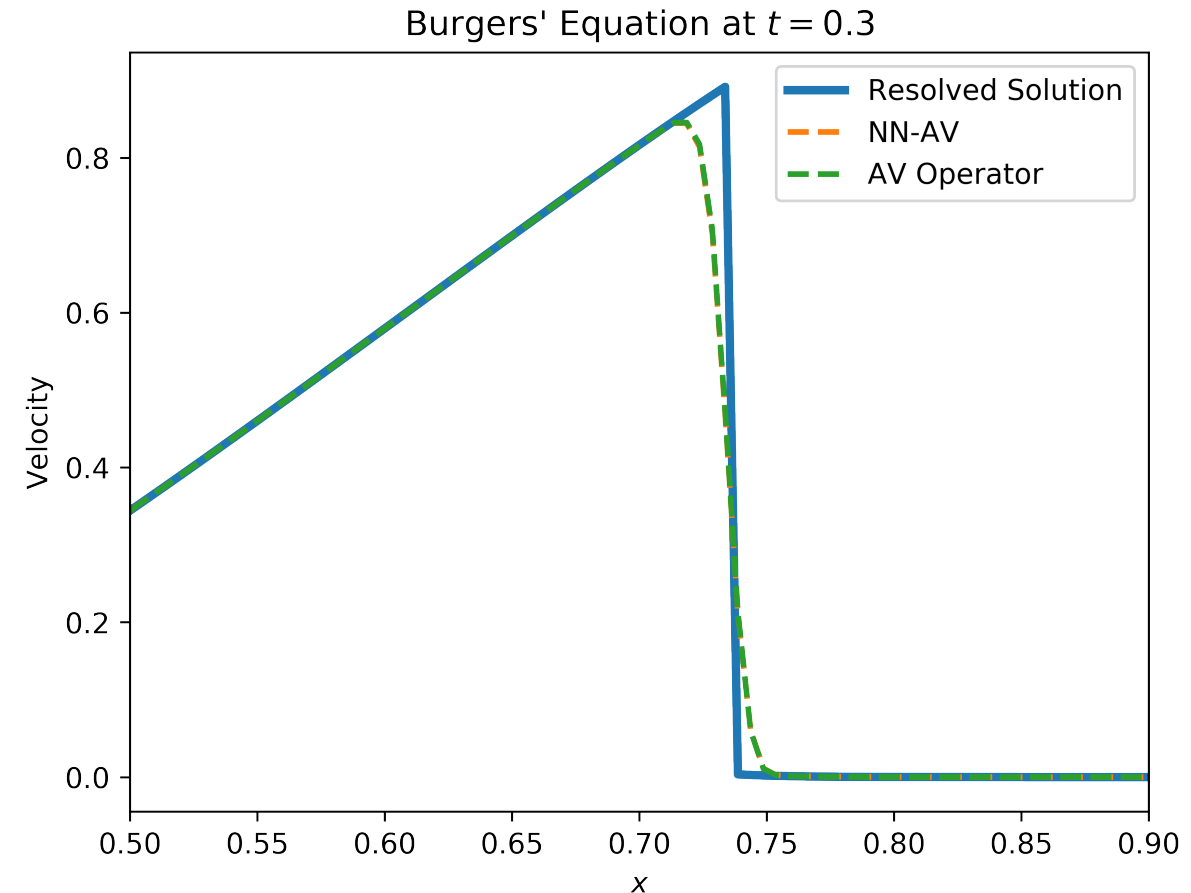


# Applying the NN-AV to the Viscous Burgers' Equation

## Relative Error in Velocity between AV Operator and NN-AV and Resolved Calculation\*

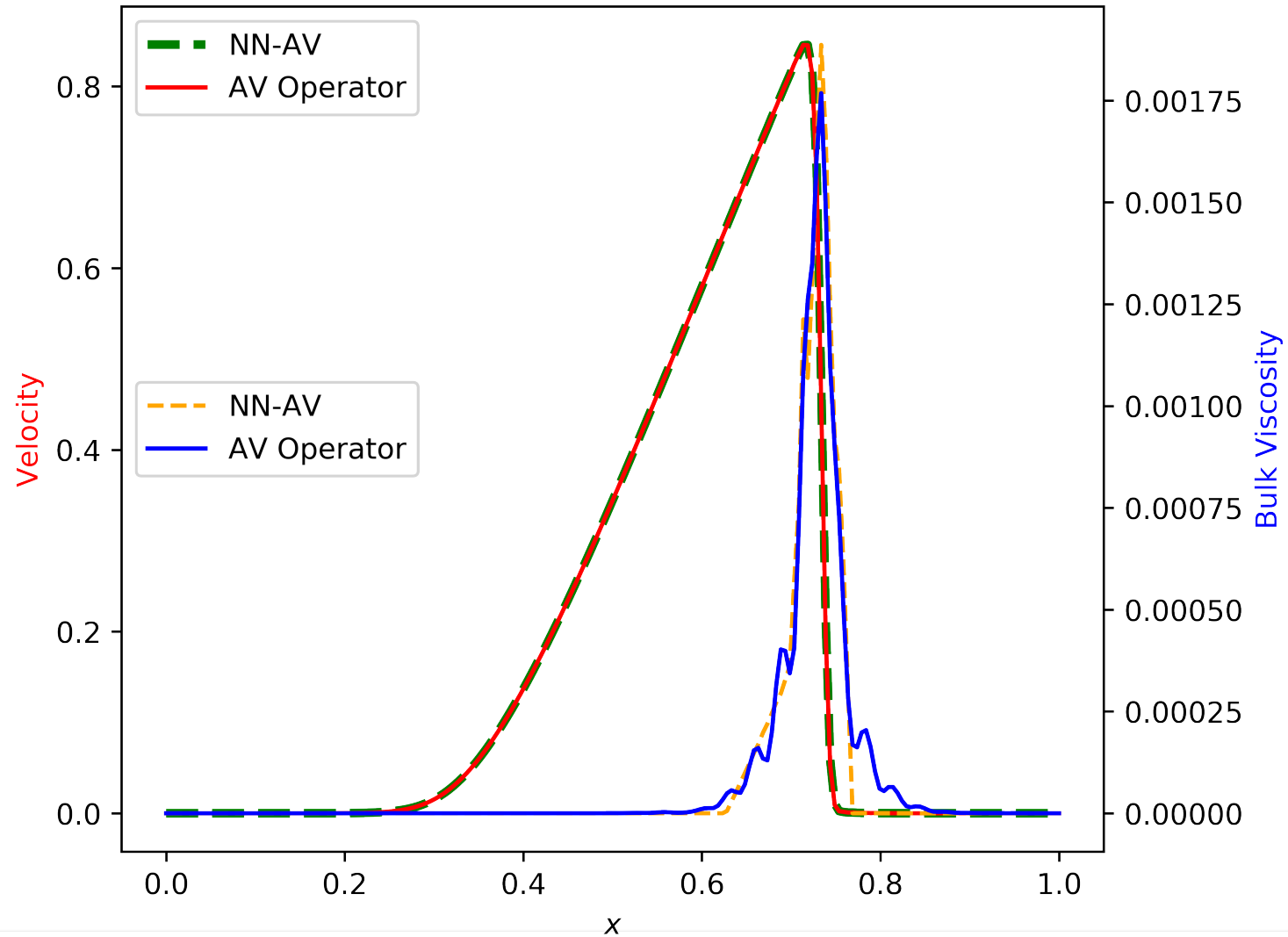
		$L_1$	$L_2$	$L_\infty$
AV Operator	Traditional	2.690e-02	1.471e-02	1.242e-02
	NN-AV	2.659e-02	1.429e-02	1.184e-02

\*Resolved calculation was run using the traditional AV operator and 10000 spatial points (50x)



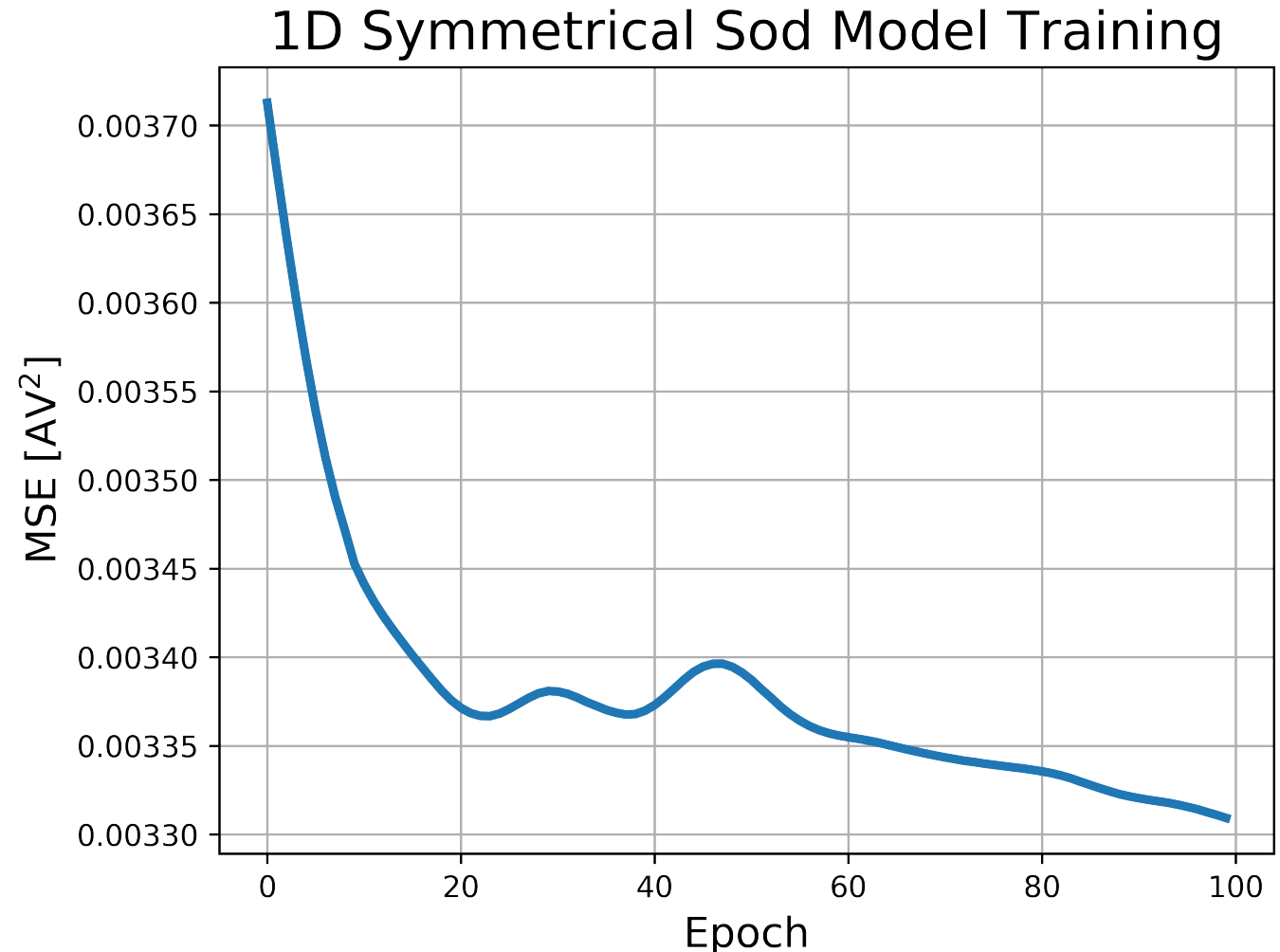
# Viscous Burgers' Equation at $t=0.3$

- The NN model follows the same structure as the traditional AV operator
- The NN-AV has the proper scaling
- The shape of NN-AV is slightly different and has smooth discontinuities



# Implementing a universal model based on the 1D Sod Shock Tube Problem

- When training a 1D model, it is biased for shocks in 1 direction
- This can be overcome by using mirroring to get symmetric training data, as though the shock was propagating in both directions
- **Epoch:** The number of iterations that the entire training dataset has been processed
- **MSE:** A loss function used to evaluate accuracy
- These are operations completed by TensorFlow



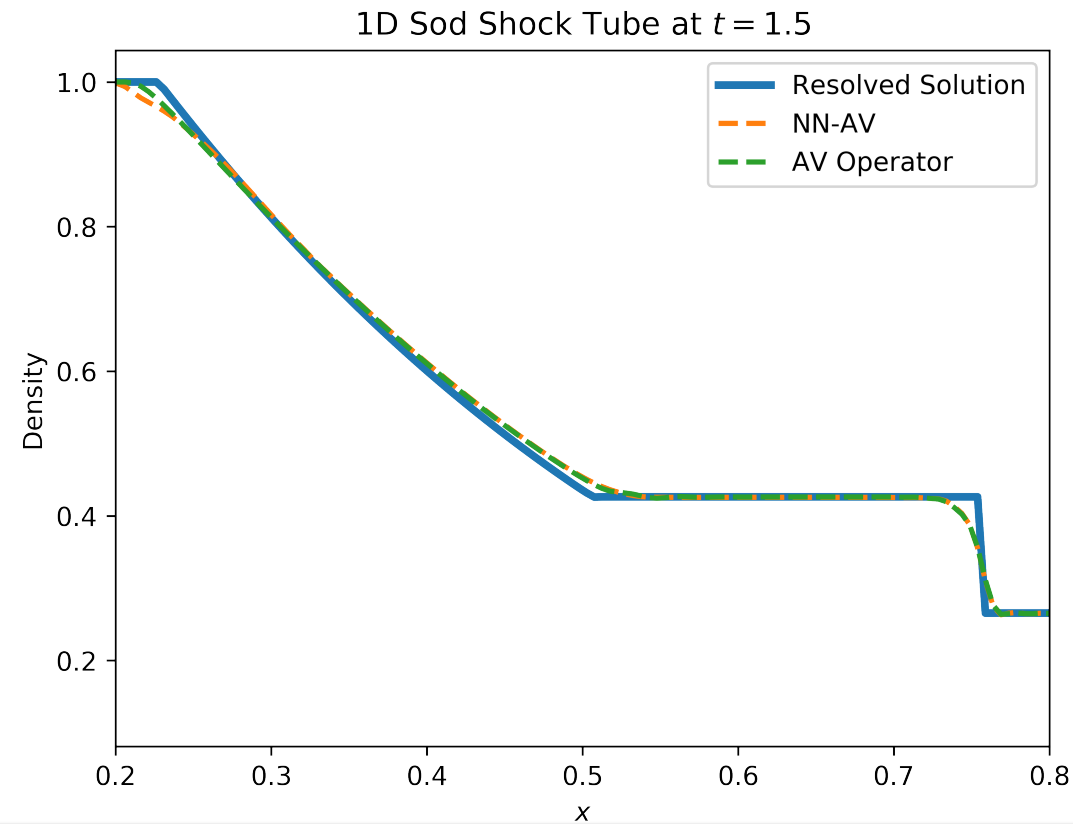


# Applying the 1D Sod Shock Tube model to itself

## Relative Error in Density between AV Operator and NN-AV and Resolved Calculation\*

		$L_1$	$L_2$	$L_\infty$
AV Operator	Traditional	8.452e-03	1.286e-03	6.035e-04
	NN-AV	9.304e-03	1.338e-03	6.074e-04

\*Resolved calculation was run using the traditional AV operator and 10000 spatial points (50x resolution)

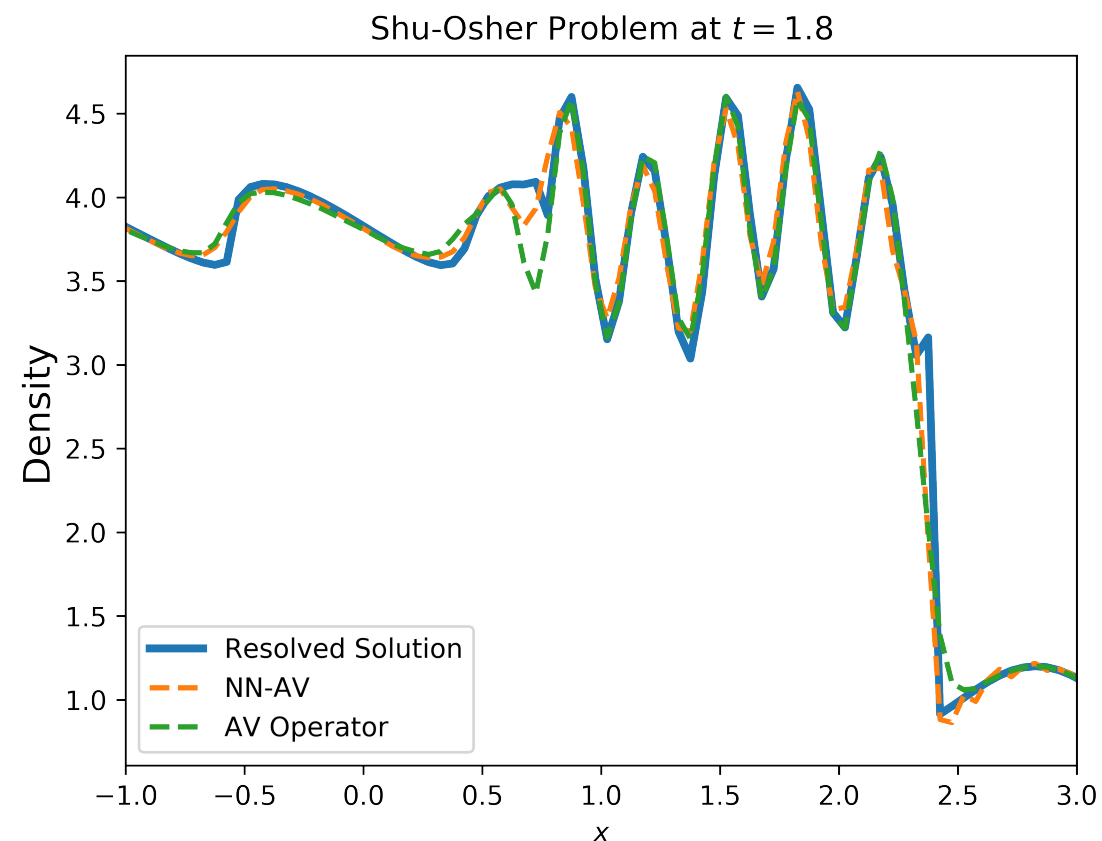


# Applying the 1D Sod Shock Tube model to the Shu-Osher Problem

## Relative Error in Density between AV Operator and NN-AV and Resolved Calculation\*

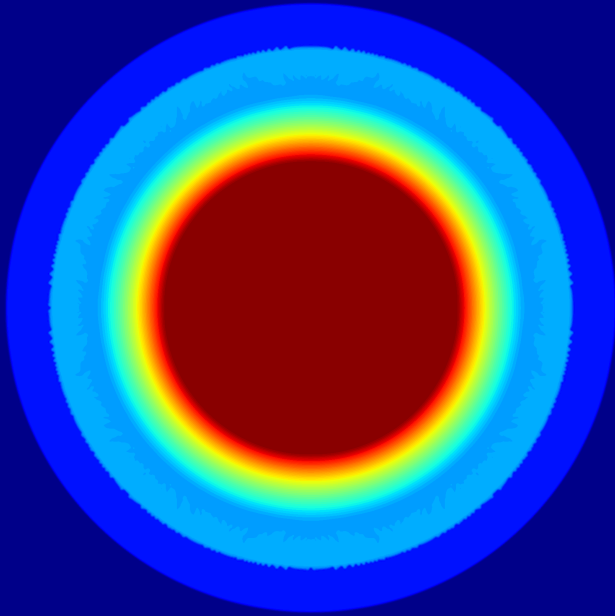
		$L_1$	$L_2$	$L_\infty$
AV Operator	Traditional	1.665e-02	2.767e-03	1.998e-03
	NN-AV	1.439e-02	2.618e-03	2.119e-03

\*Resolved calculation was run using the traditional AV operator and 10000 spatial points (50x resolution)

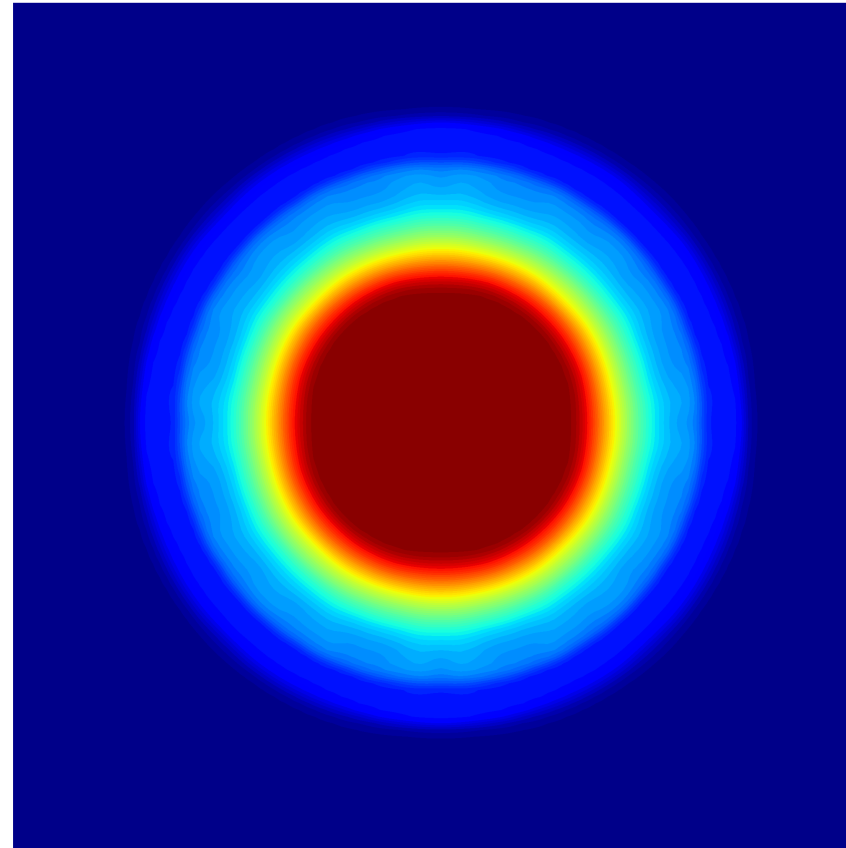


# Applying the 1D Sod Shock Tube model to the 2D problem

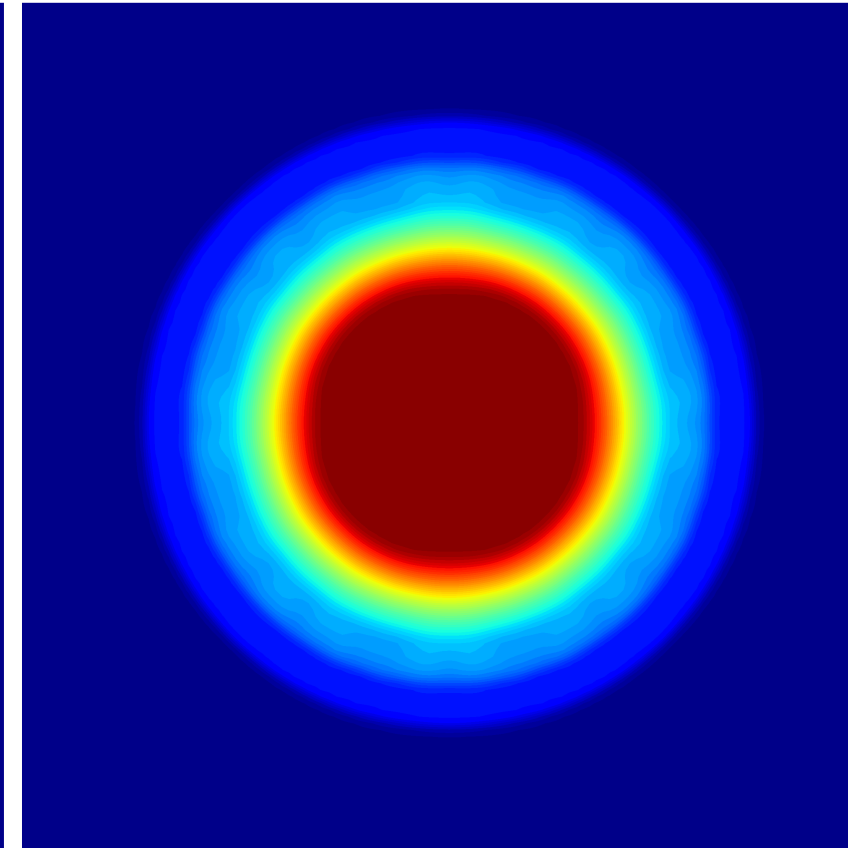
Density



**Resolved Simulation**

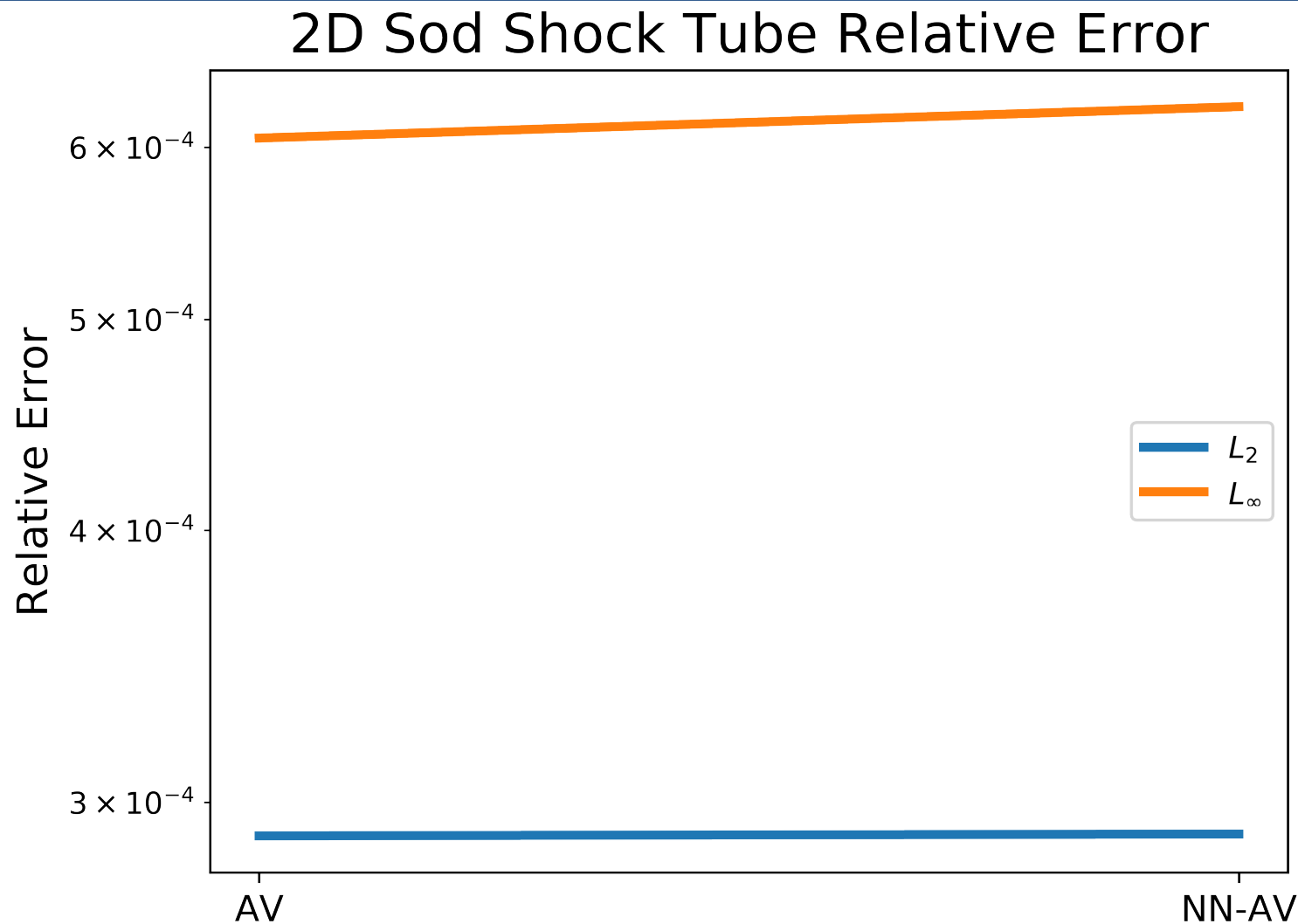


**NN-AN Operator at t=0.4**



**AV Operator at t=0.4**

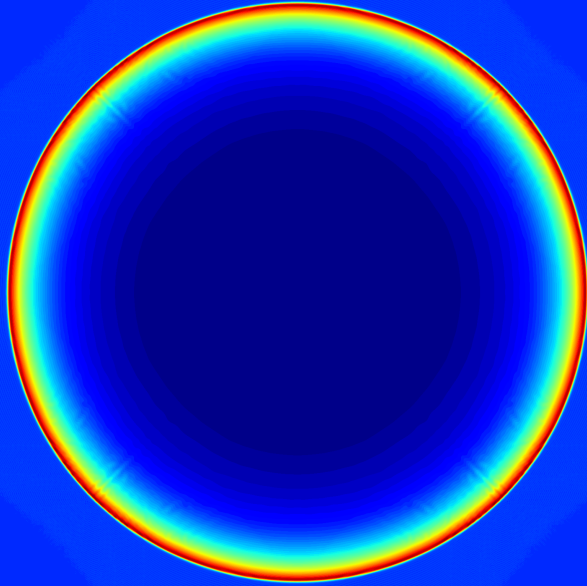
# Relative Error in Density between AV Operator and NN-AV and Resolved Calculation\* in the 2D Sod Shock Tube



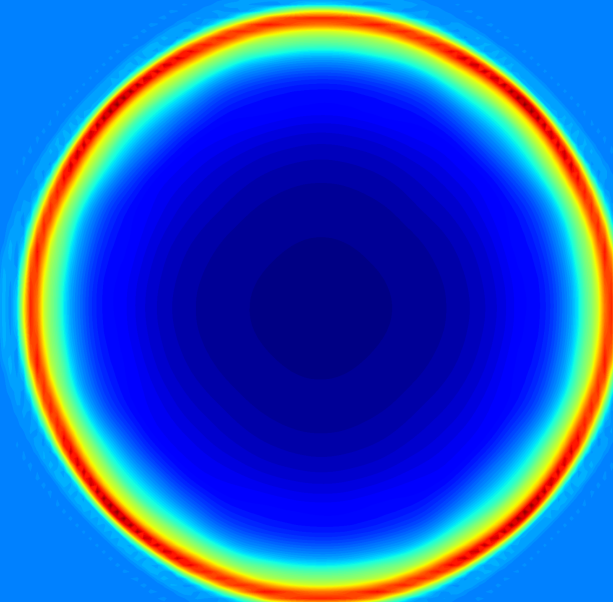
\*Resolved calculation was run using the traditional AV operator and 1048576 spatial points (64x resolution)

# Applying the 1D Sod Shock Tube model to the Sedov Blast Wave

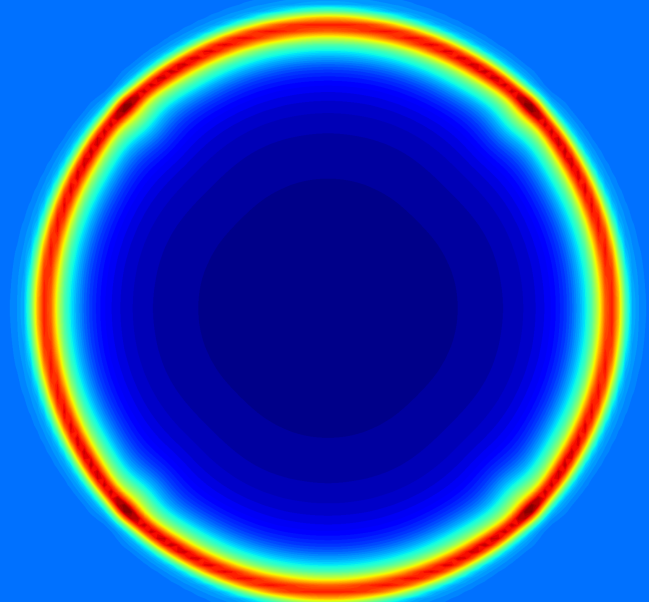
Density



**Resolved Simulation**



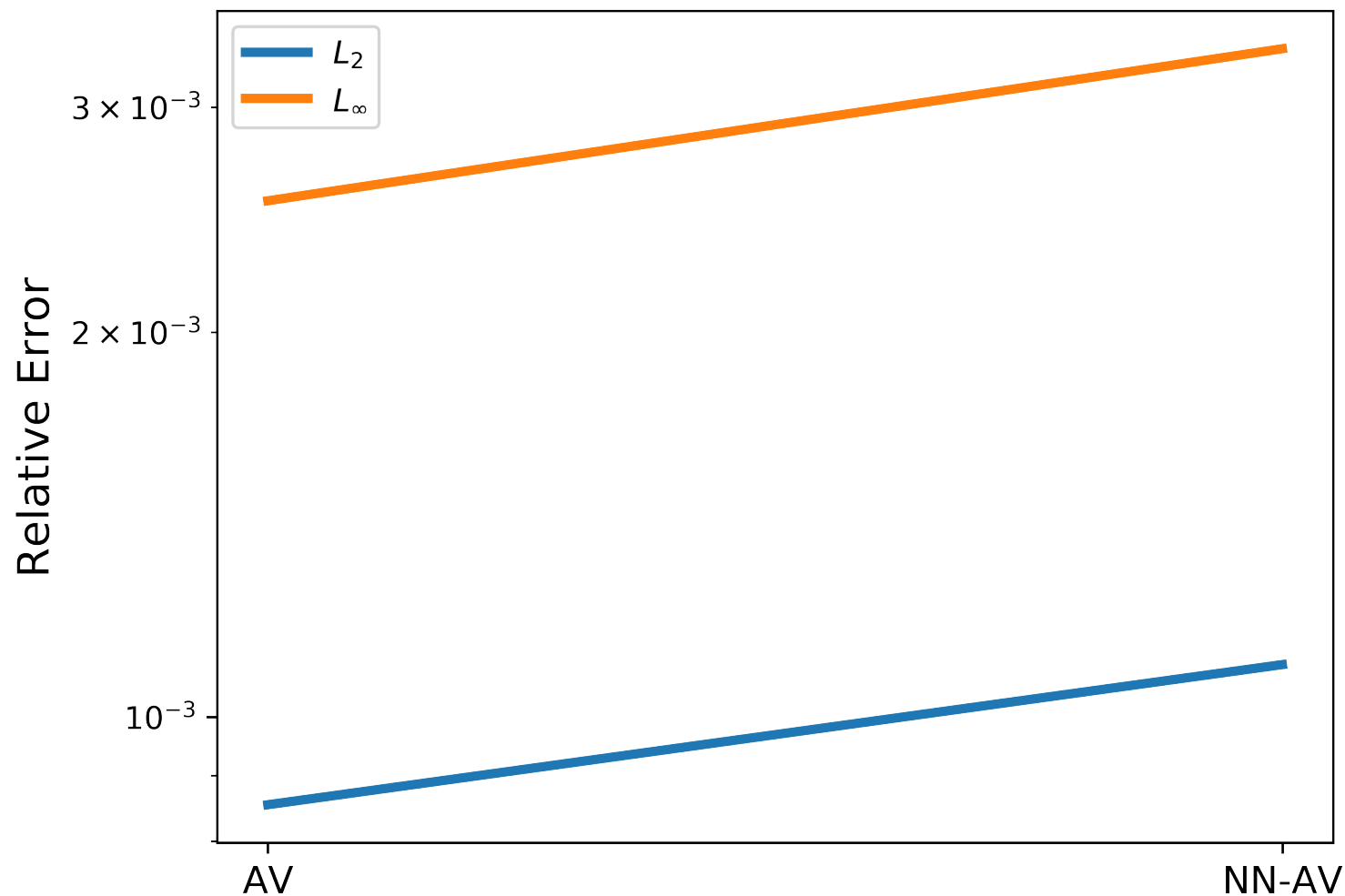
**NN-AN Operator at t=0.4**



**AV Operator at t=0.4**

# Relative Error in Density between AV Operator and NN-AV and Resolved Calculation\* in the Sedov Blast Wave

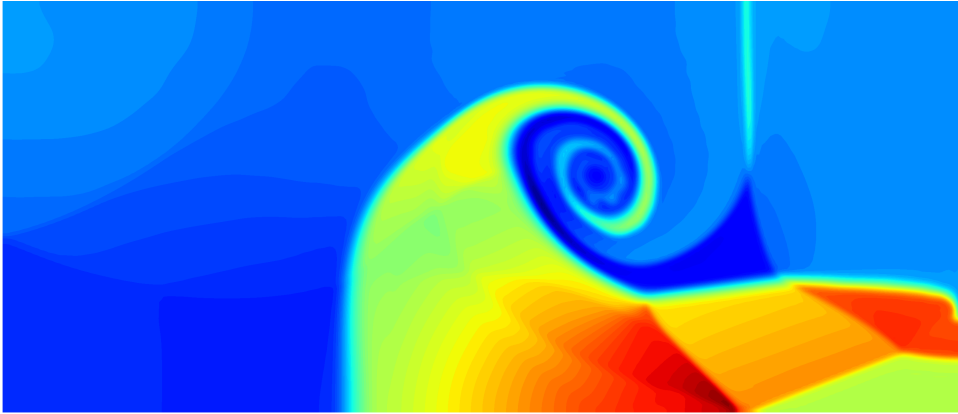
## 2D Sod Shock Tube Relative Error



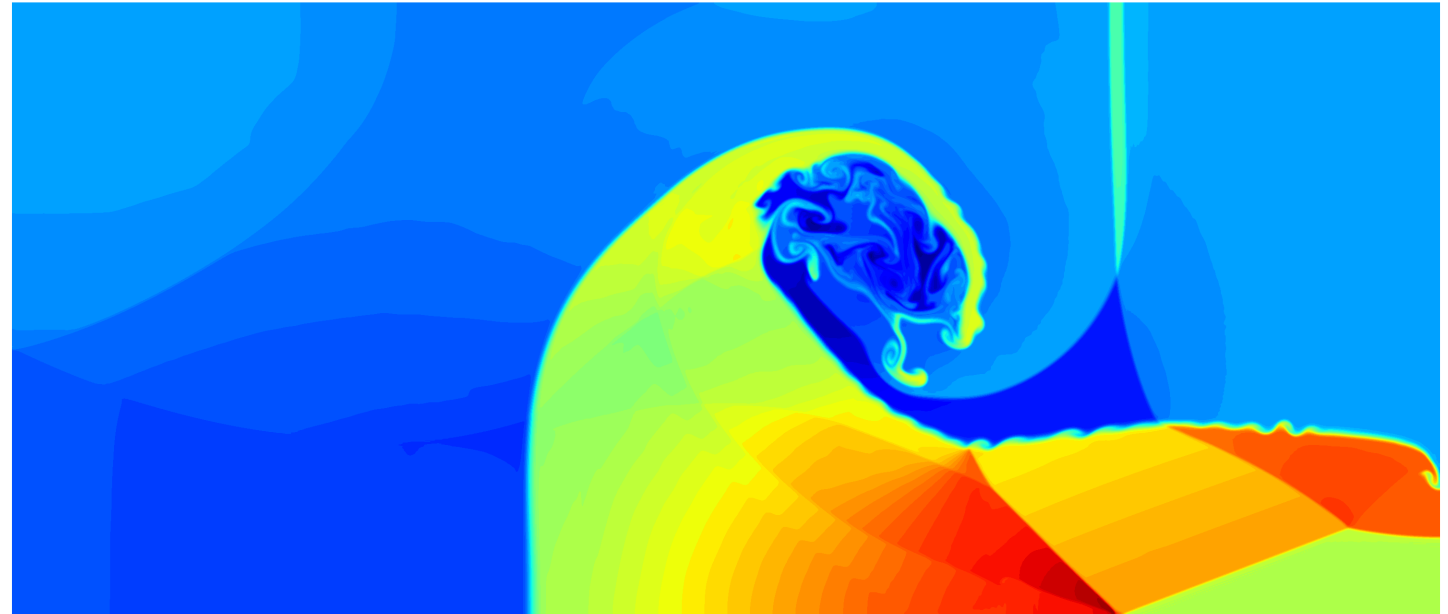
\*Resolved calculation was run using the traditional AV operator and 1048576 spatial points (64x resolution)

# Applying the 1D Sod Shock Tube model to the Triple Density Problem

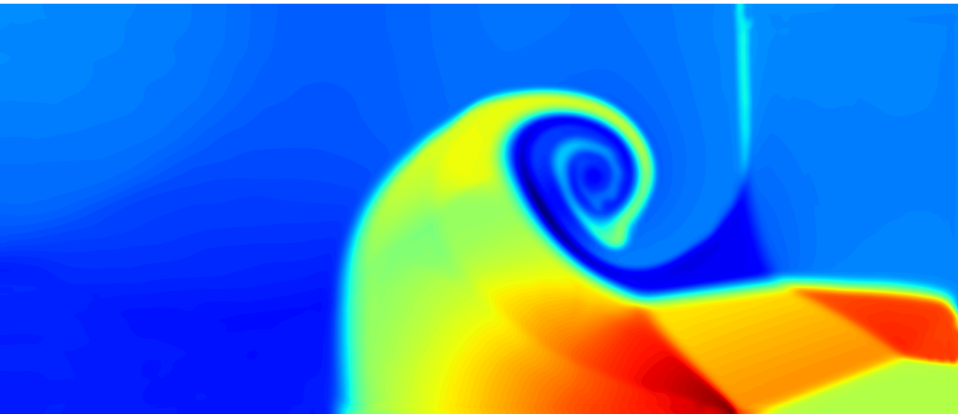
**AV Operator at  $t=0.4$**



## Resolved Simulation

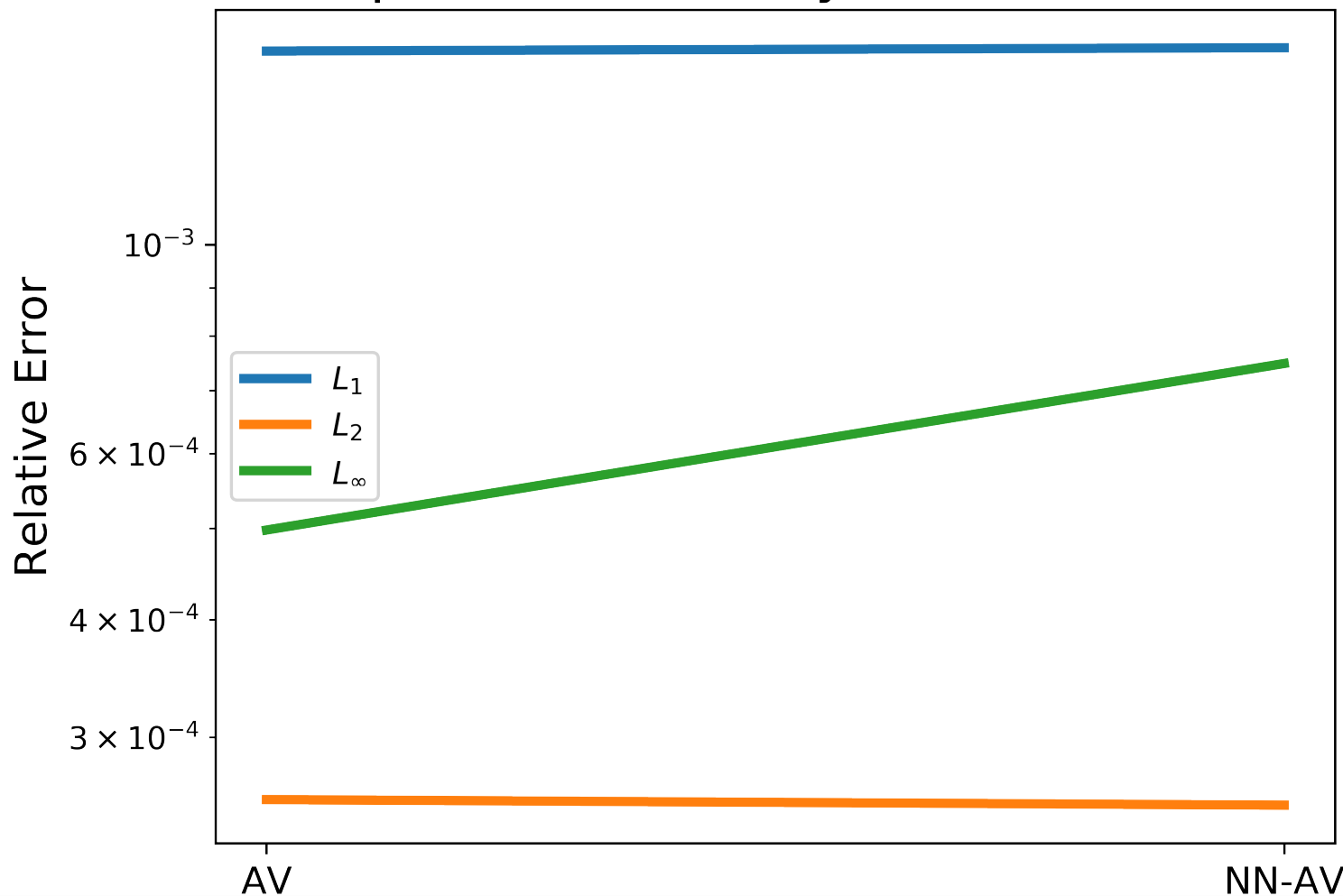


**NN-AN Operator at  $t=0.4$**



# Relative Error in Density between AV Operator and NN-AV and Resolved Calculation\* in the Triple Density Problem

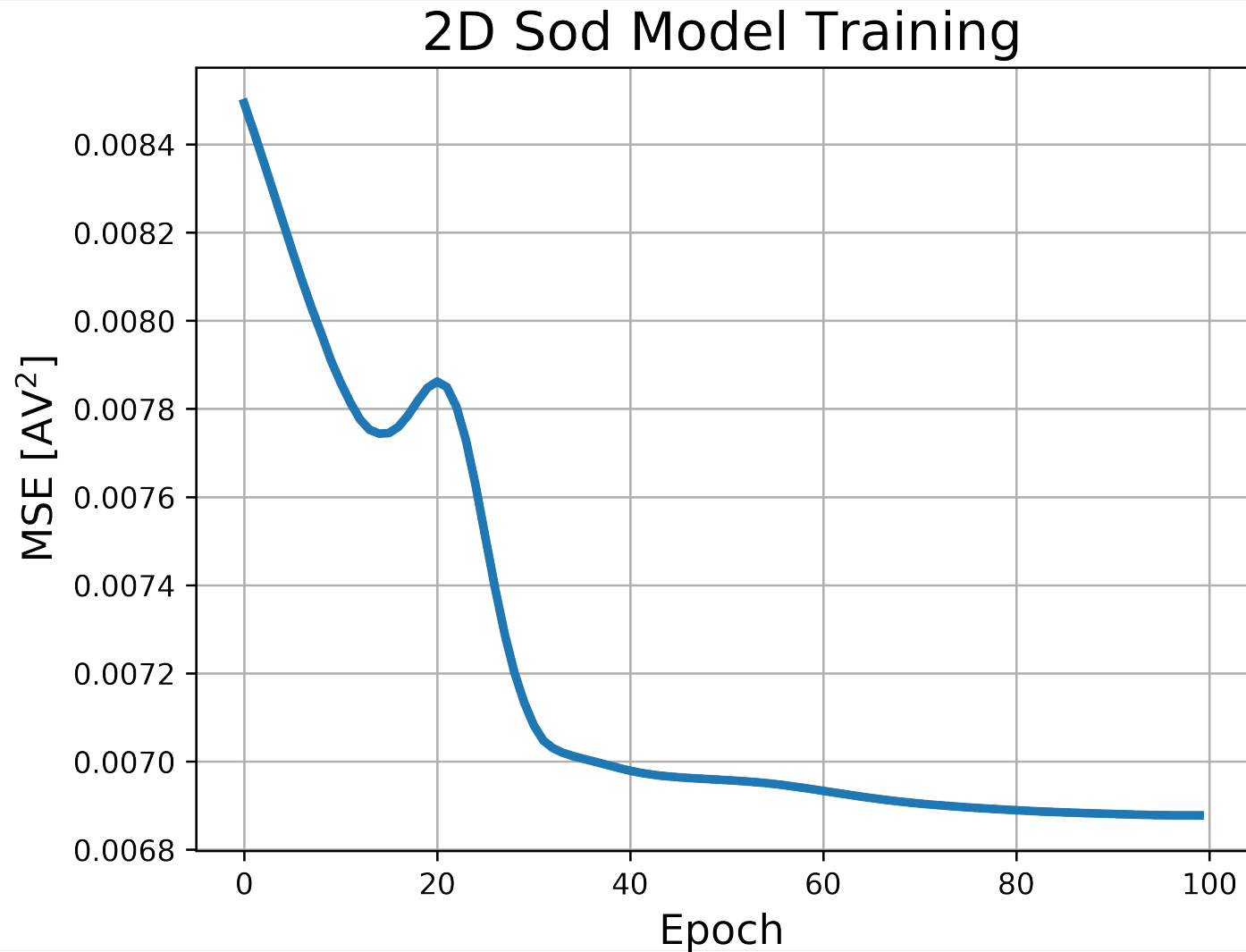
## Triple Point Density Relative Error



\*Resolved calculation was run using the traditional AV operator and 840000 spatial points (16x resolution)



# Implementing a universal model based on the 2D Sod Shock Tube Problem



# A model trained with a 2D shock dominated problem has similar accuracy to that trained with a 1D problem

## $L_2$ Relative Error in Density between AV Operator and NN-AV and Resolved Calculation

		AV	1D NN-AV	2D NN-AV
Problem	1D Sod	1.286e-03	1.345e-03	1.338e-03
	2D Sod	2.895e-04	2.901e-04	3.192e-04
	Sedov Blast Wave	8.540e-04	1.099e-03	9.812e-04
	Triple Density	1.600e-05	1.582e-05	1.824e-05

# Order of accuracy of traditional AV is high-order by construction

- The NN-AV does not explicitly create a high-order accurate model

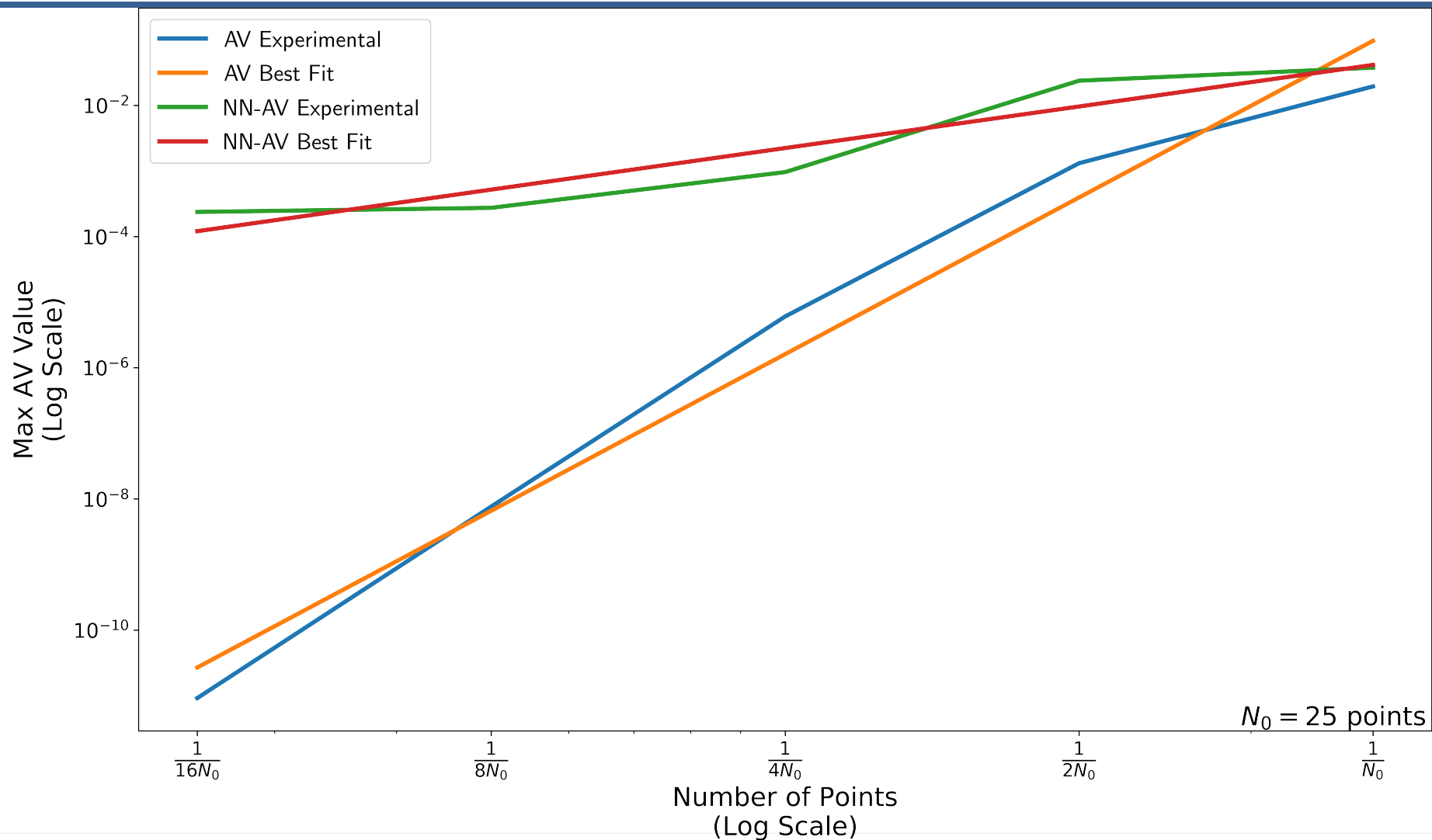
- To calculate order of accuracy

$$\log(\max(AV)) = \log(C) + p * \log(h)$$

- $h$  : number of points in the domain
- $C$  : constant
- $p$  : order of accuracy
- The max AV value was collected from different resolutions of Burgers' equation before the shock formed using both the traditional AV operator and NN-AV.

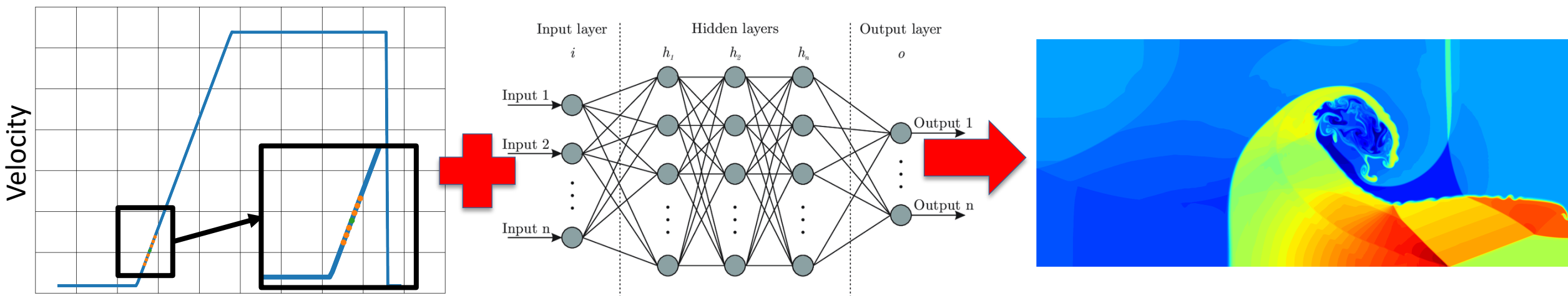
# AV Operator is 8<sup>th</sup> order accurate

## NN-AV is 2<sup>nd</sup> order accurate



# Conclusion: AV can be modeled accurately using a Neural Network

- To a reasonable degree of accuracy, neural networks can accurately to predict artificial viscosity values in shock dominated problems
- By creating a model using one shock-dominated problem as a training dataset, the model can be used to predict artificial viscosity values in other shock-dominated problems



# Future Work

- Decrease runtime
  - Optimize model prediction to decrease computation time needed
  - Optimize variable insertion to Miranda so each step doesn't require calculating AV
- Model improvement
  - Train a NN over mach numbers
  - Make a more universal model
  - Make the model high-order accurate
- Create NN for each artificial diffusivity, including:
  - Thermal conductivity
  - Vorticity
  - Shear viscosity



**Disclaimer**

This document was prepared as an account of work sponsored by an agency of the United States government. Neither the United States government nor Lawrence Livermore National Security, LLC, nor any of their employees makes any warranty, expressed or implied, or assumes any legal liability or responsibility for the accuracy, completeness, or usefulness of any information, apparatus, product, or process disclosed, or represents that its use would not infringe privately owned rights. Reference herein to any specific commercial product, process, or service by trade name, trademark, manufacturer, or otherwise does not necessarily constitute or imply its endorsement, recommendation, or favoring by the United States government or Lawrence Livermore National Security, LLC. The views and opinions of authors expressed herein do not necessarily state or reflect those of the United States government or Lawrence Livermore National Security, LLC, and shall not be used for advertising or product endorsement purposes.